

MTH 263 Practice Test #3 - Solutions

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Name _____

1. Sketch the space curve generated by the vector-valued function $r(t) = 3 \cos(t) \vec{i} + 4 \sin(t) \vec{j} + \frac{1}{2}t \vec{k}$.

Examining the x and y components only, we have:

$$x = 3 \cos(t); \quad y = 4 \sin(t)$$

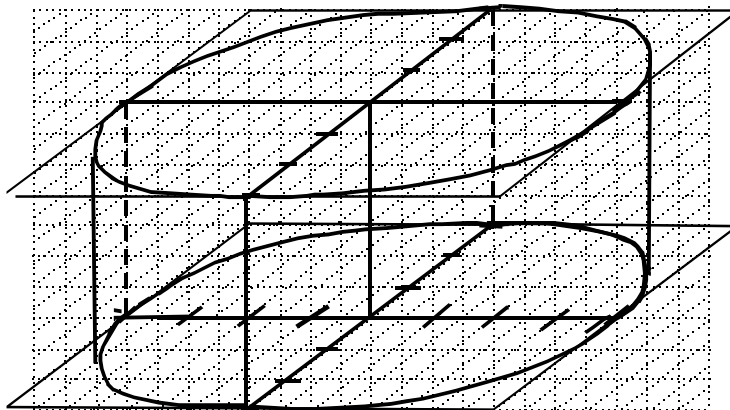
$$\Rightarrow \cos(t) = \frac{x}{3} \quad \sin(t) = \frac{y}{4}$$

$$\Rightarrow \cos^2(t) = \frac{x^2}{3^2} \quad \sin^2(t) = \frac{y^2}{4^2}$$

From the identity $\cos^2(t) + \sin^2(t) = 1$, we get

$$\frac{x^2}{3^2} + \frac{y^2}{4^2} = 1$$

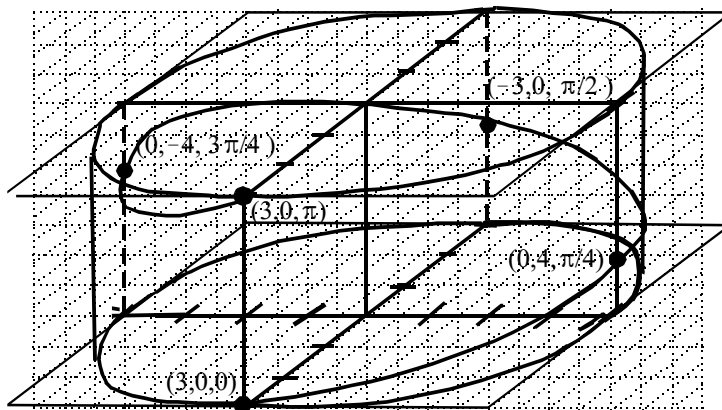
This is an ellipse, centered at the origin, with “horizontal radius” $a = 3$, and “vertical radius” $b = 4$. In 3-D, this an elliptic cylinder (shown below).



This surface is not generated by the vector function, $r(t)$, but the space curve generated by $r(t)$ lies on the inside wall of the cylinder. To graph the space curve, we'll plot a few points.

t	$x = 3 \cos(t)$	$y = 4 \sin(t)$	$z = \frac{1}{2}t$
0	3	0	0
$\frac{\pi}{2}$	0	4	$\frac{\pi}{4}$
π	-3	0	$\frac{\pi}{2}$
$\frac{3\pi}{2}$	0	-4	$\frac{3\pi}{4}$
2π	3	0	π

The graph of the space curve appears below.



2. Compute the velocity and acceleration vectors for the vector in problem 1, evaluate and graph these vectors at $t = \frac{\pi}{2}$

$$\mathbf{v}(t) = \mathbf{r}'(t) = -3 \sin(t) \mathbf{i} + 4 \cos(t) \mathbf{j} + \frac{1}{2} \mathbf{k}$$

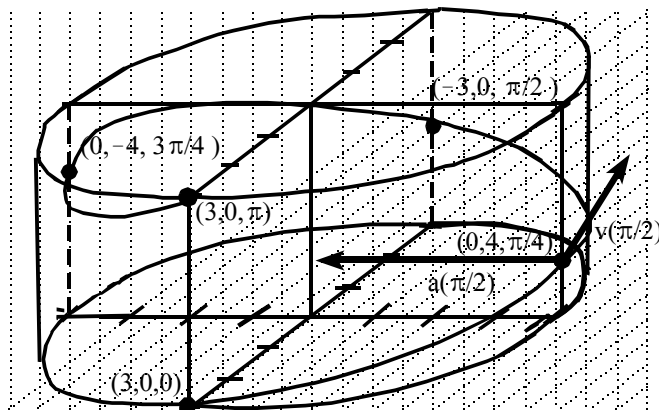
$$\mathbf{a}(t) = \mathbf{v}'(t) = -3 \cos(t) \mathbf{i} - 4 \sin(t) \mathbf{j} + 0 \mathbf{k} = -3 \cos(t) \mathbf{i} - 4 \sin(t) \mathbf{j}$$

At $t = \frac{\pi}{2}$, we have:

$$\mathbf{v}\left(\frac{\pi}{2}\right) = -3 \sin\left(\frac{\pi}{2}\right) \mathbf{i} + 4 \cos\left(\frac{\pi}{2}\right) \mathbf{j} + \frac{1}{2} \mathbf{k} = -3 \mathbf{i} + \frac{1}{2} \mathbf{k}$$

$$\mathbf{a}\left(\frac{\pi}{2}\right) = -3 \cos\left(\frac{\pi}{2}\right) \mathbf{i} - 4 \sin\left(\frac{\pi}{2}\right) \mathbf{j} = -4 \mathbf{j}$$

The vectors are shown below.



3. Evaluate: $\int_{-2}^3 (t\mathbf{i} + t^3\mathbf{j} + 4t\mathbf{k}) dt =$

The vectors is integrated “component-wise.”

$$\int_{-2}^3 (t\mathbf{i} + t^3\mathbf{j} + 4t\mathbf{k}) dt = \left(\int_{-2}^3 t dt\right) \mathbf{i} + \left(\int_{-2}^3 t^3 dt\right) \mathbf{j} + \left(\int_{-2}^3 4t dt\right) \mathbf{k} =$$

$$\left(\left[\frac{1}{2}t^2\right]_{-2}^3\right) \mathbf{i} + \left(\left[\frac{1}{4}t^4\right]_{-2}^3\right) \mathbf{j} + \left([2t^2]_{-2}^3\right) \mathbf{k} = \left(\frac{1}{2}(3)^2 - \frac{1}{2}(-2)^2\right) \mathbf{i} + \left(\frac{1}{4}(3)^4 - \frac{1}{4}(-2)^4\right) \mathbf{j} + \left(2(3)^2 - 2(-2)^2\right) \mathbf{k} =$$

$$\frac{5}{2} \mathbf{i} + \frac{65}{4} \mathbf{j} + 10 \mathbf{k}$$

4. $a(t) = 4\vec{i} + 3\vec{k}$. Compute the velocity and position vectors, given the following information:

(a) $v(0) = 4\vec{j} + \vec{k}$

(b) $r(0) = 2\vec{i}$

$$v(t) = \int a(t) dt = \int (4\vec{i} + 3\vec{k}) dt = 4t\vec{i} + 3t\vec{k} + \mathbf{C}$$

i.e., $v(t) = 4t\vec{i} + 3t\vec{k} + \mathbf{C}$

From the information given, we have: $v(0) = 4\vec{j} + \vec{k}$

$$\Rightarrow v(0) = 4(0)\vec{i} + 3(0)\vec{k} + \mathbf{C} = \mathbf{C} = 4\vec{j} + \vec{k}$$

i.e., $\mathbf{C} = 4\vec{j} + \vec{k}$

$$\Rightarrow v(t) = 4t\vec{i} + 3t\vec{k} + \mathbf{C} = 4t\vec{i} + 3t\vec{k} + (4\vec{j} + \vec{k}) = 4(t+1)\vec{i} + (3t+1)\vec{k}$$

i.e., $v(t) = 4(t+1)\vec{i} + (3t+1)\vec{k}$

To find the position function, realize that $r(t) = \int v(t) dt = \int (4(t+1)\vec{i} + (3t+1)\vec{k}) dt = (2t^2 + t)\vec{i} + (\frac{3}{2}t^2 + t)\vec{k} + C_2$

i.e., $r(t) = (2t^2 + t)\vec{i} + (\frac{3}{2}t^2 + t)\vec{k} + C_2$

From the information given, we have: $r(0) = 2\vec{i}$

$$\Rightarrow r(0) = (2(0)^2 + (0))\vec{i} + (\frac{3}{2}(0)^2 + (0))\vec{k} + C_2 = C_2 = 2\vec{i}$$

i.e., $C_2 = 2\vec{i}$

$$\Rightarrow r(t) = (2t^2 + t)\vec{i} + (\frac{3}{2}t^2 + t)\vec{k} + C_2 = (2t^2 + t)\vec{i} + (\frac{3}{2}t^2 + t)\vec{k} + 2\vec{i} = (2t^2 + t + 2)\vec{i} + (\frac{3}{2}t^2 + t)\vec{k}$$

5. Compute the speed of the vector in problem 4 at the point $t = 4$ sec.

Recall: speed = $\|v(t)\|$

$$\text{At } t = 4, \text{ speed} = \|v(4)\| = \|4((4) + 1)\vec{i} + (3(4) + 1)\vec{k}\| = \|20\vec{i} + 13\vec{k}\| = \sqrt{20^2 + 13^2} = \sqrt{569}$$

6. Given the vector $r(t) = 2\sin(t)\vec{i} + 2\cos(t)\vec{j}$, compute the vectors $\mathbf{T}(t)$, $\mathbf{N}(t)$, and evaluate them at $t = \frac{\pi}{4}$.

$$\begin{aligned} \mathbf{T}(t) &= \frac{r'(t)}{\|r'(t)\|} = \frac{2\cos(t)\vec{i} - 2\sin(t)\vec{j}}{\|2\cos(t)\vec{i} - 2\sin(t)\vec{j}\|} = \frac{2\cos(t)\vec{i} - 2\sin(t)\vec{j}}{\sqrt{4\cos^2(t) + 4\sin^2(t)}} = \frac{2\cos(t)}{\sqrt{4\cos^2(t) + 4\sin^2(t)}}\vec{i} - \frac{2\sin(t)}{\sqrt{4\cos^2(t) + 4\sin^2(t)}}\vec{j} \\ &= \frac{2\cos(t)}{\sqrt{4(\cos^2(t) + \sin^2(t))}}\vec{i} - \frac{2\sin(t)}{\sqrt{4(\cos^2(t) + \sin^2(t))}}\vec{j} = \frac{2\cos(t)}{2}\vec{i} - \frac{2\sin(t)}{2}\vec{j} = \cos(t)\vec{i} - \sin(t)\vec{j} \end{aligned}$$

At $t = \frac{\pi}{4}$, we have $\mathbf{T}\left(\frac{\pi}{4}\right) = \cos\left(\frac{\pi}{4}\right)\vec{i} - \sin\left(\frac{\pi}{4}\right)\vec{j} = \frac{\sqrt{2}}{2}\vec{i} - \frac{\sqrt{2}}{2}\vec{j}$

$$\begin{aligned} \mathbf{N}(t) &= \frac{\mathbf{T}'(t)}{\|\mathbf{T}'(t)\|} = \frac{-\sin(t)\vec{i} - \cos(t)\vec{j}}{\|-\sin(t)\vec{i} - \cos(t)\vec{j}\|} = \frac{-\sin(t)\vec{i} - \cos(t)\vec{j}}{\sqrt{(-\sin(t))^2 + (-\cos(t))^2}} = \frac{-\sin(t)\vec{i} - \cos(t)\vec{j}}{\sqrt{\sin^2(t) + \cos^2(t)}} = -\sin(t)\vec{i} - \cos(t)\vec{j} \end{aligned}$$

At $t = \frac{\pi}{4}$, we have $\mathbf{N}\left(\frac{\pi}{4}\right) = -\sin\left(\frac{\pi}{4}\right)\vec{i} - \cos\left(\frac{\pi}{4}\right)\vec{j} = -\frac{\sqrt{2}}{2}\vec{i} - \frac{\sqrt{2}}{2}\vec{j}$

7. For the vector in problem 6, evaluate \mathbf{a}_T , and \mathbf{a}_N at $t = \frac{\pi}{4}$.

First, we need to compute the acceleration, $a(t)$.

$$a(t) = v'(t) = r''(t) = -\sin(t)\vec{\mathbf{i}} - \cos(t)\vec{\mathbf{j}}$$

$$\mathbf{a}_T = a \circ \mathbf{T} = \left(-\sin(t)\vec{\mathbf{i}} - \cos(t)\vec{\mathbf{j}}\right) \circ \left(\cos(t)\vec{\mathbf{i}} - \sin(t)\vec{\mathbf{j}}\right) = -\sin(t)\cos(t) + \cos(t)\sin(t) = 0$$

$$\mathbf{a}_N = a \circ \mathbf{N} = \left(-\sin(t)\vec{\mathbf{i}} - \cos(t)\vec{\mathbf{j}}\right) \circ \left(-\sin(t)\vec{\mathbf{i}} - \cos(t)\vec{\mathbf{j}}\right) = \sin^2(t) + \cos^2(t) = 1$$

8. Compute $\frac{\partial}{\partial x} [\sin(x^2y) + x^3 - 5y^4]$

When we compute the partial derivative with respect, we treat all variables except for x as though they were constants.

$$\frac{\partial}{\partial x} [\sin(x^2y) + x^3 - 5y^4] = \underbrace{\cos(x^2y) \cdot 2x + 3x^2 + 0}_{\text{chain rule}} = \cos(x^2y) \cdot 2x + 3x^2$$

9. Given $f(x, y) = \sin(x - 2y)$, show that $f_{xy} = f_{yx}$

$$f_{xy} = \frac{\partial}{\partial y} \left(\frac{\partial}{\partial x} [f(x, y)] \right) = \frac{\partial}{\partial y} \left(\frac{\partial}{\partial x} [\sin(x - 2y)] \right) = \frac{\partial}{\partial y} (\cos(x - 2y)) = -\sin(x - 2y) \cdot (-2) = 2\sin(x - 2y)$$

$$f_{yx} = \frac{\partial}{\partial x} \left(\frac{\partial}{\partial y} [f(x, y)] \right) = \frac{\partial}{\partial x} \left(\frac{\partial}{\partial y} [\sin(x - 2y)] \right) = \frac{\partial}{\partial x} (\cos(x - 2y) \cdot (-2)) = \frac{\partial}{\partial x} (-2\cos(x - 2y)) = -2(-\sin(x - 2y)) = 2\sin(x - 2y)$$

Hence, $f_{xy} = f_{yx}$

10. Find the relative maxes and mins of the function $f(x, y) = x^3 - y^3 - 3xy + 4$

To find the critical numbers, we set the partial derivatives equal to 0.

$$\frac{\partial f}{\partial x} = 3x^2 - 3y = 0 \Rightarrow x^2 = y$$

$$\frac{\partial f}{\partial y} = -3y^2 - 3x = 0 \Rightarrow y^2 = -x$$

Substituting $x^2 = y$ into $y^2 = -x$, we get $x^4 = -x \Rightarrow x^4 + x = 0 \Rightarrow x(x^3 + 1) = 0 \Rightarrow x = -1, 0$

$x = -1 \Rightarrow y = 1 \Rightarrow (-1, 1)$ is a critical point.

$x = 0 \Rightarrow y = 0 \Rightarrow 0, 0$ is a critical point.

Now we need to test these. We need the second partial derivatives.

$$\frac{\partial^2 f}{\partial x^2} = 6x$$

$$\frac{\partial^2 f}{\partial y^2} = -6y$$

$$\frac{\partial^2 f}{\partial y \partial x} = -3$$

Recall: If $f_{xx}f_{yy} - (f_{xy})^2 > 0$, then there is a relative extreme.

If $f_{xx}f_{yy} - (f_{xy})^2 < 0$, then there is NO relative extreme.

At $(-1, 1)$, $\frac{\partial^2 f}{\partial x^2} = -6$, $\frac{\partial^2 f}{\partial y^2} = -6$, and $\frac{\partial^2 f}{\partial y \partial x} = -3$

$\Rightarrow f_{xx}f_{yy} - (f_{xy})^2 = (-6)(-6) - (-3)^2 = 27 > 0$, Therefore, we have an extreme.

Since $\frac{\partial^2 f}{\partial x^2} = -6 < 0$, the surface is concave down, so we have a relative max at $(-1, 1)$

i.e., $(-1, 1, 5)$ is a local max.

At the point $(0, 0)$ $\frac{\partial^2 f}{\partial x^2} = 0$, $\frac{\partial^2 f}{\partial y^2} = 0$, and $\frac{\partial^2 f}{\partial y \partial x} = -3$

$$\Rightarrow f_{xx}f_{yy} - (f_{xy})^2 = (0)(0) - (-3)^2 = -9 < 0$$

Therefore, we have neither a rel max nor a rel min at $(0, 0, 4)$